This listing of claims will replace all prior versions, and listings, of claims in the application:

Claim 1 (canceled)

Claim 2 (currently amended): An image sensing apparatus having a distance measuring unit, comprising:

an image sensing element to form an object image which enters via a photographing optical system;

a distance measuring unit to measure distances to a plurality of points within a photographing frame using an optical path different from an optical path of photographing optical system;

a determination unit to determine a relationship between a distance measuring result of the distance measuring unit and a drive amount of the photographing optical system, on the basis of the distance measuring result upon measuring a distance to a first point of the plurality of points by the distance measuring unit and a change in contrast of the object image formed at a position corresponding to the first point on the image sensing element when a focal point position of the photographing optical system has changed; and

a control unit to control the focal point position of the photographing optical system, on the basis of a distance measuring result of the distance measuring unit at a second point of the plurality of points, which is different from the first point and the relationship determined by the determination unit

~~The image sensing apparatus according to claim 1~~,

wherein the distance measuring unit comprises:

a distance calculation unit to calculate distances to objects present at the plurality of points by detecting image signals of the objects present at the plurality of points; and

a setting unit to set a highest-contrast point of plurality of points as the first point, and to set a point corresponding to the nearest distance to the object calculated by the distance calculation unit as the second point.

Claim 3 (currently amended): The image sensing apparatus according to claim ~~1~~ 2, wherein the distance measuring unit comprises a principal object detection unit to detect a location of a principal object from the plurality of points, and

the determination unit comprises a setting unit to set a point where the principal object is present as the second point.

Claim 4 (original): The image sensing apparatus according to claim 3, wherein the principal object detection unit detects a point, at which the distance measuring result indicates a nearest distance, of the plurality of points as the point where the principal object is present.

Claim 5 (currently amended): The image sensing apparatus according to claim ~~1~~ 2, wherein the distance measuring unit measures distances to objects present at the plurality of points by a passive or active method.

Claim 6 (currently amended): The image sensing apparatus according to claim ~~1~~ 2, wherein the distance measuring unit comprises a principal object detection unit to detect a principal object on the basis of the distance measuring result, and the determination unit comprises a setting unit to set, as the first point, a point corresponding to a distance near a current focal point position of a photographing lens of the distance measuring results at the plurality of points, and to set a point where the principal object is present as the second point.

Claims 7-20 (canceled)